

Hyunchang Kang

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Sungkyunkwan university
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EDUCATION

Mar. 2021 ~ Present	Sungkyunkwan University Department of Mechanical Engineering <i>Advisor: Hyouk Ryeol Choi</i> <i>Ph.D. Student</i> GPA: 4.35 / 4.5	Suwon, Korea
Mar. 2015 ~ Feb. 2021	Hansung University Department of Mechanical System Engineering Thesis: Multi-legged Walking Robot Using Complex Linkage Structure <i>B.S. in Mechanical System Engineering</i> GPA: 4.0 / 4.5	Seoul, Korea

RESEARCH INTERESTS

- Mobile robots path planning
- Human-robot interaction
- Sensor fusion

PUBLICATIONS (SCIE/ESCI)

1. Minh Thang Bui, **Hyun Chang Kang**, Hyouk Ryeol Choi*, "Enhancing End-of-Arm Radar-enabled Safety System by Deep Learning Technique", *IEEE SENSORS JOURNAL*, December 2025.
2. Seung Jae Moon, Hongsik Yim, **Hyunchang Kang**, Jae Yoon Shim, Dawoon Jung, and Hyouk Ryeol Choi*, "Safety-Critical Reactive Motion using Constrained Variable Admittance Control with Dual-Type Proximity Sensors", *IEEE Robotics and Automation Letters*, vol. 10, no. 9, pp. 8890-8897, September 2025.
3. **Hyunchang Kang**, Hongsik Yim, Hyukjae Sung, Hyouk Ryeol Choi*, "Adaptive Measurement Model-Based Fusion of Capacitive Proximity Sensor and LiDAR for Improved Mobile Robot Perception", *IEEE Robotics and Automation Letters*, vol. 10, no. 1, pp. 836-843, January 2025.
4. Hongsik Yim, **Hyunchang Kang**, Tien Dat Nguyen and Hyouk Ryeol Choi*, "Electromagnetic Field & ToF Sensor Fusion for Advanced Perceptual Capability of Robots", *IEEE Robotics and Automation Letters*, vol. 9, no. 5, pp. 4846-4853, May 2024.
5. Hongsik Yim, **Hyunchang Kang**, Seungjae Moon, Yeeun Kim, Tien Dat Nguyen, and Hyouk Ryeol

Choi*, "Multi-functional safety sensor coupling capacitive and inductive measurement for physical human-robot interaction", *SENSORS AND ACTUATORS A: PHYSICAL*, Volume 354, May 2023.

PUBLICATIONS (DOMESTIC)

1. 임상현, 이동훈, 강현창, 김상현. (2021). 복합 링크기구를 이용한 다족 보행로봇. 한국기계기공학회지, 20(11), 74-79.

CONFERENCES

1. **Hyunchang Kang**, Hongsik Yim, Hyukjae Sung, and Hyouk Ryeol Choi*, "Adaptive Measurement Model-Based Fusion of Capacitive Proximity Sensor and LiDAR for Improved Mobile Robot Perception", IEEE International Conference on Robotics and Automation (ICRA), Atlanta, USA (May. 2025) - Oral
2. Hongsik Yim, **Hyunchang Kang**, Tien Dat Nguyen, and Hyouk Ryeol Choi*, "Electromagnetic Field & ToF Sensor Fusion for Advanced Perceptual Capability of Robots", IEEE CASE 2024, Bari, Italy (Aug. 2024) - Oral
3. 임홍식, Tien Dat Nguyen, 김예은, 강현창, 최혁렬, "A/D 변환시간 제어를 이용한 전자기장 듀얼타입 근접센서 개발", 제 16회 한국로봇종합학술대회, 2021.05.19~ 05.22, Pyeongchang, Korea (May. 2021) - Poster

PATENTS

1. 임홍식, 강현창, 한성진, 이현용, 이윤행, "벤더블 센서 플랫폼", KR-Application No. 10-2024-0202353
2. 임홍식, 강현창, 이윤행, "통합형 센서 플랫폼", KR-Application No. 10-2024-0177906
3. 강현창, 임상현, 이동훈, 김상현, "Robot walking system adopting complex link structure", KR-Registration No. 1024697720000

PROJECTS

- 실시간 충돌상황 감지 및 회피 기능이 탑재된 로봇충돌 안전용 SoC 통합플랫폼 개발, 산업통상자원부, Korea / Development of proximity sensor module for Human-Robot Interaction (Jan. 2024 ~ Dec. 2026)
- 다양한 환경에서도 적용 가능한 Universal Mobile Robot 플랫폼 설계, 성균관대학교, Korea / Development of modeling, and autonomous driving (Mar. 2022 ~ Aug. 2023)

EXPERIENCE

- (Student Researcher) AIDIN ROBOTICS (Anyang, Gyeonggi-do)
Period : Mar. 2021 ~ Dec. 2023
Task : Development of proximity sensor and mobile robot applications

EXHIBITION

- 2023 로보월드, 산업통상자원부 주최/ 에이딘로보틱스 로봇 근접 및 접촉 안전 센서 시연/ KINTEX (11 Oct. 2023 - 14 Oct. 2023)
- 2022 로보월드, 산업통상자원부 주최/ 에이딘로보틱스 로봇 근접 및 접촉 안전 센서 시연/ KINTEX (26 Oct. 2022 - 29 Oct. 2022)

2022 - 29 Oct. 2022)

- 2021 로보월드, 산업통상자원부 주최/ 에이딘로보틱스 로봇 근접 및 접촉 안전 센서 시연/ KINTEX (27 Oct. 2021 - 30 Oct. 2021)